TM-313-A

## ERRATUM AND ADDENDUM TO TM-313

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Both Eqs. (1) and (9) are approximate equations. For Eq. (1) the approximation assumes that  $\frac{x}{\beta} << 1$  and terms of the second and higher orders in  $\frac{x}{\beta}$  are neglected. These conditions are satisfied for the example cases given on pp. 3 and 4.

For Eq. (9) the approximation assumes that  $\frac{\Delta\beta}{\beta}$  << 1 and  $\frac{\Delta B!}{B!}$  << 1, and terms of the second and higher orders in  $\frac{\Delta\beta}{\beta}$  and  $\frac{\Delta B!}{B!}$  are neglected. These conditions are <u>not</u> satisfied for the example cases given on pp. 6 and 7. The results are, therefore, invalid.

Eq. (10) shows that  $\frac{\Delta\beta}{\beta}$  (if << 1) is a sinusoidal function of  $\theta$  with amplitude  $\sqrt{U}$ . For  $\sqrt{U}$  > 1, then, at some  $\theta$ -locations  $\frac{\Delta\beta}{\beta}$  < -1 and the modified  $\overline{\beta}$  =  $\beta$  +  $\Delta\beta$  < 0 which is certainly not meaningful. This is another indication that Eq. (9) and its solution Eq. (10) are invalid when  $\frac{\Delta\beta}{\beta}$  =  $\sqrt{U}$  > 1.

For the case of one  $\delta$ -function focusing bump the exact solution can be obtained using the transfer matrix. The transfer matrix around the entire closed orbit plus the bump ( $\epsilon_0$ ) is

$$\begin{pmatrix} 1 & 0 \\ -\varepsilon_0 & 1 \end{pmatrix} \begin{bmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \cos 2\pi \nu + \begin{pmatrix} \alpha_0 & \beta_0 \\ -\gamma_0 & -\alpha_0 \end{pmatrix} \sin 2\pi \nu \end{bmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ -\varepsilon_{o} & 1 \end{pmatrix} \cos 2\pi \nu + \begin{pmatrix} \alpha_{o} & \beta_{o} \\ -(\gamma_{o} + \varepsilon_{o} \alpha_{o}) & -(\alpha_{o} + \varepsilon_{o} \beta_{o}) \end{pmatrix} \sin 2\pi \nu$$

where, as before,  $\epsilon_o \equiv \frac{(\Delta B \, ! \, \ell)_o}{B \rho}$ . The modified "tune"  $\overline{\nu}$  and  $\beta$ -function at the bump  $\overline{\beta}_o$  are, therefore, given by

$$\begin{cases}
\cos 2\pi \overline{\nu} = \cos 2\pi \nu - \frac{\varepsilon_0 \beta_0}{2} \sin 2\pi \nu \\
\overline{\beta}_0 \sin 2\pi \overline{\nu} = \beta_0 \sin 2\pi \nu.
\end{cases}$$
(1A)

As  $\varepsilon_0$  varies from zero to either positive or negative values stability limits cos  $2\pi\overline{\nu}=\pm 1$  will be encountered at certain values of  $\varepsilon_0$ . Beyond these values of  $\varepsilon_0$ ,  $|\cos 2\pi\overline{\nu}|>1$  and the motion is unstable. At the stability limits the modified  $\beta$ -function  $\overline{\beta}$  is  $\infty$  everywhere except at discrete  $\theta$ -locations where  $\overline{\beta}=0$ , namely  $\frac{\Delta\beta}{\beta}\equiv\frac{\overline{\beta}-\beta}{\beta}$  is  $\infty$  everywhere except at these discrete  $\theta$ -locations where  $\frac{\Delta\beta}{\beta}=-1$ . Although at the stability limit this exact  $\frac{\Delta\beta}{\beta}$  is hardly sinusoidal, one may expect that the stability limits correspond roughly to  $\sqrt{\overline{\upsilon}}=1$  when the "approximate"  $\overline{\beta}$  as given by Eq. (10) also goes to zero at these discrete  $\theta$ -locations. Eq. (13) gives, then, for the stability limits

$$\frac{\varepsilon_0 \beta_0}{2} = \pm \sin 2\pi \nu \quad \text{"approximate"} \quad (2A)$$

while the exact conditions are given by Eq. (1A) as

$$\frac{\varepsilon_0^{\beta_0}}{2} = \frac{\cos 2\pi \nu \mp 1}{\sin 2\pi \nu}$$

$$= -\frac{1}{\cos 2\pi \nu \pm 1} \sin 2\pi \nu. \text{ exact}$$
 (3A)

The exact and the "approximate" conditions are identical when  $\nu$  = (integer)  $\pm \frac{1}{4}$ .

For the main ring  $v \approx 20\frac{1}{4}$ . Both Eqs. (2A) and (3A) give for the stability limits

$$\frac{\varepsilon_0^{\beta_0}}{2} = \pm 1$$

or, for  $\beta_0 \approx 100 \text{ m}$ 

$$\varepsilon_0 = \pm \frac{2}{\beta_0} \approx \pm 0.02 \text{ m}^{-1}.$$

Missing one quadrupole ( $\varepsilon_o$  = ±0.04 m<sup>-1</sup>) will take us beyond the stability limit. The most we can tolerate is missing  $\frac{1}{2}$  of a quadrupole.

The "invariant" U is clearly also an approximate invariant valid only when  $\frac{\Delta\beta}{\beta}$  << 1. We can put U in a more conventional form.

$$U = \left(\frac{\Delta\beta}{\beta}\right)^{2} + \frac{1}{4\nu^{2}} \left[\frac{d}{d\theta} \left(\frac{\Delta\beta}{\beta}\right)\right]^{2}$$

$$= \left(\frac{\Delta\beta}{\beta}\right)^{2} + \frac{1}{4} \left[\beta \frac{d}{dz} \left(\frac{\Delta\beta}{\beta}\right)\right]^{2}$$

$$= \left(\frac{\Delta\beta}{\beta}\right)^{2} + \left[-\frac{\beta'}{2} \frac{\Delta\beta}{\beta} + \frac{(\Delta\beta)'}{2}\right]^{2}$$

$$= \left(\frac{\Delta\beta}{\beta}\right)^2 + \alpha^2 \left(\frac{\Delta\beta}{\beta} - \frac{\Delta\alpha}{\alpha}\right)^2 \tag{4A}$$

where prime means  $\frac{d}{dz}$  and  $\alpha = -\frac{\beta'}{2}$ ,  $\Delta \alpha = -\frac{(\Delta \beta)'}{2}$ .

D. A. Edwards gave the exact form of this invariant as

$$U = \frac{\left(\frac{\Delta\beta}{\beta}\right)^2 + \alpha^2 \left(\frac{\Delta\beta}{\beta} - \frac{\Delta\alpha}{\alpha}\right)^2}{1 + \frac{\Delta\beta}{\beta}}.$$
 (5A)

His derivation is given below: Consider two locations 1 and 2 around the closed orbit with no focusing bump in between. The transfer matrices from locations 1 and 2 all the way around the closed orbit are respectively

$$\overline{M}_{1} = \cos 2\pi \overline{v} + \overline{J}_{1} \sin 2\pi \overline{v}$$

$$= \cos 2\pi \overline{v} + (J_{1} + \Delta J_{1}) \sin 2\pi \overline{v}$$

and

$$\overline{M}_2 = \cos 2\pi \overline{\nu} + \overline{J}_2 \sin 2\pi \overline{\nu}$$
$$= \cos 2\pi \overline{\nu} + (J_2 + \Delta J_2) \sin 2\pi \overline{\nu}.$$

Writing the transfer matrix from location 1 to location 2 as  $M_{12}$  (there is no need for a bar on top because there is no bump between locations 1 and 2) the relation  $\overline{M}_2 = M_{12}M_1M_{12}^{-1}$  leads to

$$J_2 + \Delta J_2 = M_{12} (J_1 + \Delta J_1) M_{12}^{-1}$$

Remembering that  $J_2 = M_{12}J_1M_{12}^{-1}$  we get

$$\Delta J_2 = M_{12} \Delta J_1 M_{12}^{-1}$$

which shows that the determinant of  $\Delta J$  is invariant within a bump-free region. We can, thus, write

$$U = -|\Delta J| = (\Delta \alpha)^2 - (\Delta \beta)(\Delta \gamma) = invariant.$$

Substituting

$$\Delta \gamma = \frac{1 + (\alpha + \Delta \alpha)^2}{\beta + \Delta \beta} - \frac{1 + \alpha^2}{\beta}$$

$$= -\frac{\frac{\Delta \beta}{\beta} + \alpha^2 \left[ \frac{\Delta \beta}{\beta} - 2 \frac{\Delta \alpha}{\alpha} - \left( \frac{\Delta \alpha}{\alpha} \right)^2 \right]}{\beta \left( 1 + \frac{\Delta \beta}{\beta} \right)}$$

we get directly the expression (5A).

I am grateful to Dr. S. Ohnuma for pointing out the error in TM-313 and to Dr. D. Edwards for the derivation of the exact expression of the invariant U, and to both of them for several illuminating discussions.